Digital universal particle concentration sensor

PMS5003 series data manual

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|----------|--------------|---------|------------|
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Main characteristics

- Zero false alarm rate
- ◆ Real-time response
- ◆ Correct data
- ♦ Minimum distinguishable particle diameter :0.3 micrometer
- ◆ High anti-interference performance because of the patent structure of six sides shielding
- Optional direction of air inlet and outlet in order to adapt the different design

Overview

PMS5003 is a kind of digital and universal particle concentration sensor, which can be used to obtain the number of suspended particles in the air, i.e. the concentration of particles, and output them in the form of digital interface. This sensor can be inserted into variable instruments related to the concentration of suspended particles in the air or other environmental improvement equipments to provide correct concentration data in time.

Working principle

Laser scattering principle is used for such sensor, i.e. produce scattering by using laser to radiate suspending particles in the air, then collect scattering light in a certain degree, and finally obtain the curve of scattering light change with time. In the end, equivalent particle diameter and the number of particles with different diameter per unit volume can be calculated by microprocessor based on MIE theory. Please find the functional diagram of each part of sensor from Figure 1 as follows.

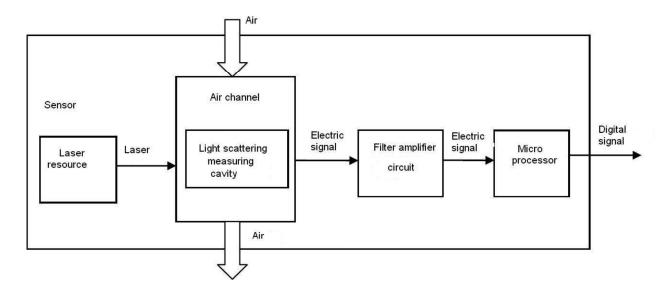


Figure 1 Functional block diagram of sensor

Technical Index

| Parameter | Index | unit |
|---------------------------|--------------------------|-------------------|
| Range of measurement | 0.3~1.0; 1.0~2.5; 2.5~10 | Micrometer (µ m) |
| Counting Efficiency | 50%@0.3µ m 98%@>=0.5µ m | |
| Effective Range (PM2.5 | 0~500 | μ g/m³ |
| standard) | | |
| Maximum Range (PM2.5 | ≥1000 | μ g/m³ |
| standard) * | | |
| Resolution | 1 | μ g/m³ |
| Maximum Consistency Error | ±10%@100~500µ g/m³ | |
| (PM2.5 standard data)* | ±10µ g/m³ @0~100µ g/m³ | |
| Standard Volume | 0.1 | Litre (L) |
| Single Response Time | <1 | Second (s) |
| Total Response Time | ≤10 | Second (s) |
| DC Power Supply | Typ:5.0 Min:4.5 Max: 5.5 | Volt (V) |
| Active Current | ≤100 | Milliampere (mA) |
| Standby Current | ≤200 | Microampere (µ A) |
| Interface Level | L <0.8 @3.3 H >2.7@3.3 | Volt (V) |
| Working Temperature Range | -10~+60 | °C |
| Working Humidity Range | 0~99% | |
| Storage Temperature Range | -40~+80 | °C |
| MTTF | ≥3 | Year (Y) |
| Physical Size | 50×38×21 | Millimeter (mm) |

Note 1: Maximum range means that the highest output value of the PM2.5 standard data is not less than 1000.

Note 2: "PM2.5 standard data" is the "data2" in the appendix.

Pin Definition

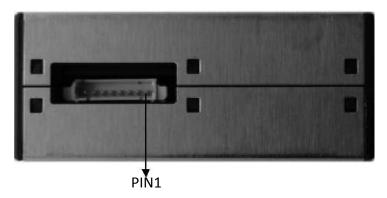


Figure 2 Connector Definition

| PIN1 | VCC | Positive power 5V |
|--------|-------|---|
| PIN2 | GND | Negative power |
| PIN3 | SET | Set pin /TTL level@3.3V, high level or suspending is normal working status, while low level is sleeping mode. |
| PIN4 | RX | Serial port receiving pin/TTL level@3.3V |
| PIN5 | TX | Serial port sending pin/TTL level@3.3V |
| PIN6 | RESET | Module reset signal /TTL level@3.3V, low reset. |
| PIN7/8 | NC | |

Output result

Mainly output as the quality and number of each particles with different size per unit volume, the unit volume of particle number is 0.1L and the unit of mass concentration is μ g/m³.

There are two options for digital output: passive and active. Default mode is active after power up. In this mode sensor would send serial data to the host automatically .The active mode is divided into two sub-modes: stable mode and fast mode. If the concentration change is small the sensor would run at stable mode with the real interval of 2.3s.And if the change is big the sensor would be changed to fast mode automatically with the interval of 200~800ms, the higher of the concentration, the shorter of the interval.

Typical Circuit

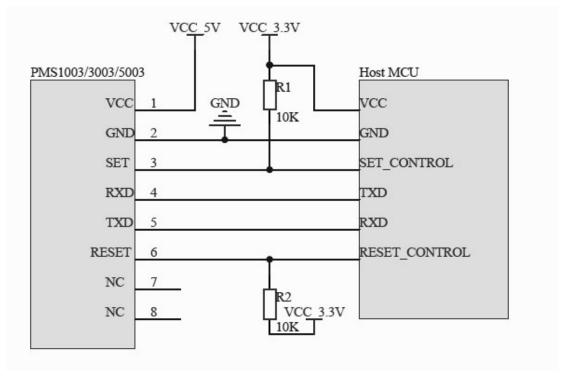


Figure 3 Typical Circuit

Typical Output Characteristic

Definition of axis Y: PM2.5 concentration , unit: μ g/m³ Definition of axis X: number of samples, unit: time

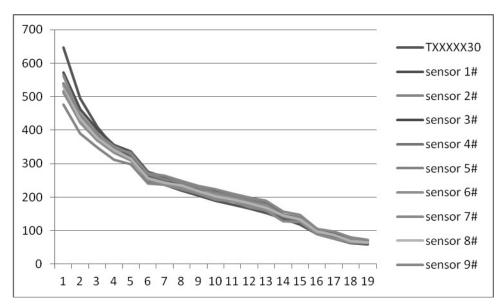


Figure 4-1 Consistency at 20 °C

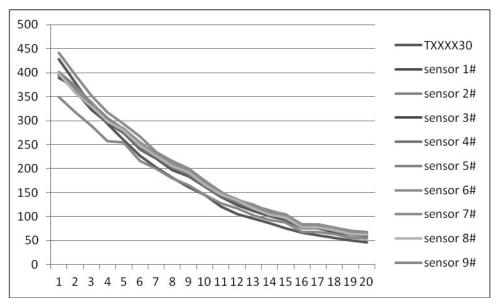


Figure 4-2 Consistency at 43 °C

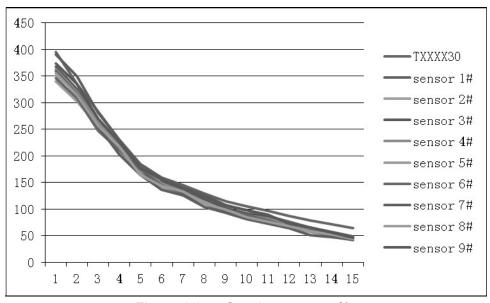


Figure 4-3 Consistency at -5°C

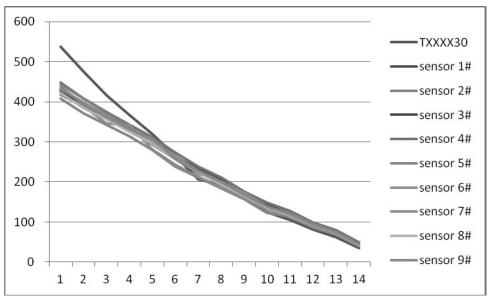


Figure 4-4 Consistency after 30 days' running

Relationship of Temperature and Consistency

Definition of axis Y: Maximum Error Modulus(%)

Definition of axis X: Temperature($^{\circ}$ C)

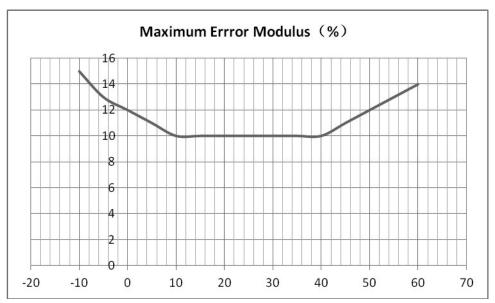


Figure 5 Consistency Vs Temperature

Endurance Characteristics

| No | Item | Test Method | Characteristics | n |
|----|--------------|--|----------------------------|-----------|
| 1 | Long Running | 1. 10 m² closed Lab, 20~25 ℃ , | 10 samples during | C n=30 |
| 1 | Long Kuming | humidity 30%~70%, particle | 0~500µ g/m ³ | C=0 |
| | | generator and air cleaner | 0 300µ g/III | C-0 |
| | | 2. DC 5V power supply | 0~100µ g/m³ | |
| | | 3. Check consistency after 720 | Maximum Error≤ | |
| | | hours' running | $\pm 15 \mu \text{ g/m}^3$ | |
| 2 | High | 1. 10 m² constant temperature Lab | <u>-</u> 13μ g/III | n=10 |
| | Temperature | 2. 43°C, humidity 70%, | 100~500µ g/m³ | C=0 |
| | Operation | 3. particle generator and air | Maximum Error≤ | C-0 |
| | Operation | cleaner | $\pm 15\%$ | |
| | | | 1576 | |
| | | | | |
| 3 | Cold | , | FAN does not | n-10 |
| 3 | | 1. 10 m² constant temperature Lab | screeched | n=10 |
| | Operation | 25°C, humidity 30%, | Screecheu | C=0 |
| | | 3. particle generator and air | | |
| | | cleaner | | |
| | | 4. DC 5V power supply | | |
| 4 | N/H I' | 5. Check consistency | <u> </u> | |
| 4 | Vibration | 1. 10 m² closed Lab,, 20 °C, humidity | | n=5 |
| | | 50%, particle generator and air | | C=0 |
| | | cleaner | | |
| | | 2. DC 5V power supply and check | | |
| | | consistency | | |
| | | 3. Frequency: 50Hz. | | |
| | | 4. acceleration: 9.8/ S ² . | | |
| | | 5. Direction: X、Y、Z | | |
| | | 6. Vibration Amplitude: ±2mm. | | |
| | | 7. Time: X、Y、Z –way, Per 1 hour | | |
| 5 | High | Constant temperature cabinet | 10 samples during | n=10 |
| | Temperature | 2. 70°C, humidity 90%~95, | 0~500µ g/m ³ | C=0 |
| | and Humidity | 3. Check consistency after 500 | F. G/ · · · | |
| | Storage | hours' storage | 0~100µ g/m³ | |
| | | | Maximum Error≤ | |
| 6 | Cold Storage | Constant temperature cabinet | $\pm 10 \mu \text{ g/m}^3$ | n=10 |
| | | 230°C, humidity 90%~95, | | C=0 |
| | | 3. Check consistency after 500 | 100~500µ g/m³ | |
| | | hours' storage | Maximum Error≤ | |
| | | | ±10% | |
| 7 | Variation of | 4. 10 m² closed Lab,, 20 °C, humidity | | n=5 |
| / | variation of | 4. 10 III closed Lab,, 20 C, numidity | | n=5 |

| | Power Supply | | 50%, particle generator and air | | C=0 |
|----|--------------|----|---|------------------|------|
| | | | cleaner | FAN does not | |
| | | | | screeched | |
| | | 5. | Power varies as the cycles of 4.5V | | |
| | | | to 5.5V ,then 5.5V to 4.5V with | | |
| | | | the pace of 0.1V/min for 2 hours. | | |
| | | 6. | Check consistency during | | |
| | | | Variation | | |
| 8 | Power On-Off | 1. | 10 $\mbox{\em m}^{\mbox{\tiny 2}}$ closed Lab, , 20 $^{\circ}\mbox{\em C}$, humidity | | n=10 |
| | Cycle | | 50%, particle generator and air | | C=0 |
| | | | cleaner | | |
| | | 2. | DC 5V power supply, keep On-Off | | |
| | | | frequency 0.5Hz for 72 hours and | | |
| | | | check consistency | | |
| 9 | Sleep Set | 1. | 10 m^2 closed Lab, , 20 $^{\circ}\text{C}$, humidity | | n=10 |
| | On-Off | | 50%, particle generator and air | | C=0 |
| | Cycle | | cleaner | | |
| | | 2. | DC 5V power supply, keep Sleep | | |
| | | | Set Pin High-Low frequency 0.5Hz | | |
| | | | for 72 hours and check | | |
| | | | consistency | | |
| 10 | Laser On-Off | 1. | 10 m ² closed Lab,, 20 °C, humidity | | n=10 |
| | Cycle | | 50%, particle generator and air | | C=0 |
| | | | cleaner | | |
| | | 2. | keep laser On-Off frequency | | |
| | | | 50Hz for 240 hours and check | | |
| | | | consistency | | |
| 11 | Salt Spray | | industrial salt water, hydrolysis | No rust and | n=1 |
| | | _ | ray 100 hours, clean with | discoloration of | C=0 |
| | | | rified water and store for 48 | metal parts | |
| | | ho | urs | | |

Circuit Attentions

- DC 5V power supply is needed because the FAN should be driven by 5V. But the high level of data pin is 3.3V. Level conversion unit should be used if the power of host MCU is 5V.
- 2) The SET and RESET pins are pulled up inside so they should not be connected if without usage.
- 3) PIN7 and PIN8 should not be connected.
- 4) Stable data should be got at least 30 seconds after the sensor wakeup from the sleep mode because of the fan's performance.

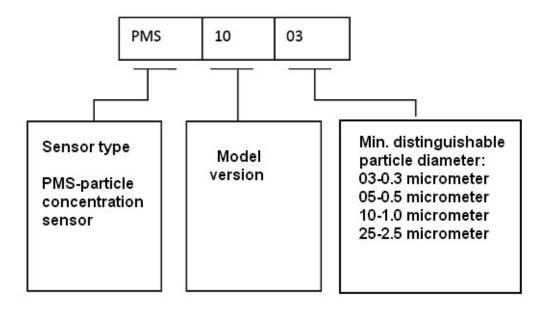
Installation Attentions

- 1) Metal shell is connected to the GND so be careful not to let it shorted with the other parts of circuit except GND.
- 2) The best way of install is making the plane of inset and outset closely to the plane of the host. Or some shield should be placed between inset and outset in order to prevent the air flow from inner loop.
- 3) The blowhole in the shell of the host should not be smaller than the inset.
- 4) The sensor should not be installed in the air flow way of the air cleaner or should be shielded by some structure.
- 5) The sensor should be installed at least 20cm higher than the grand in order to prevent it from blocking by the floc dust.
- 6) Do not break up the sensor.
- 7) M2 self-tapping strew should be used to fix the sensor but it should not be deeper than 5mm into the sensor.

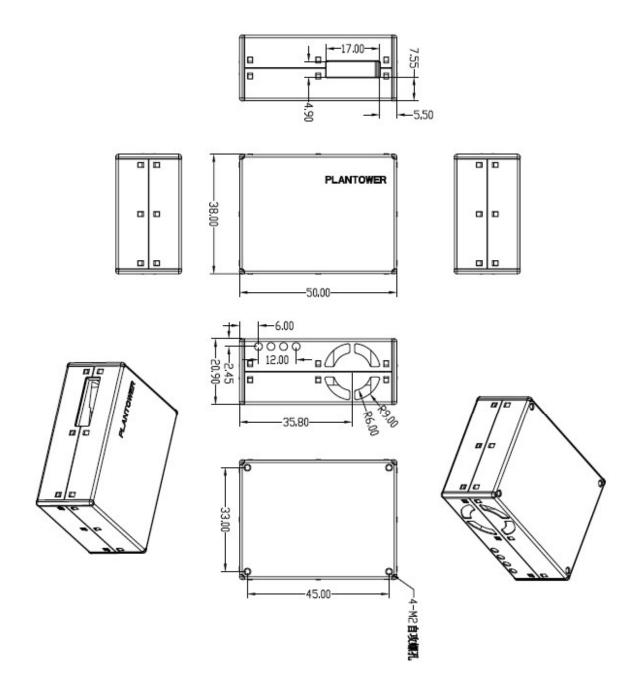
Other Attentions

- Only the consistency of all the PM sensors of PLANTOWER is promised and ensured. And the sensor should not be checked with any third party equipment.
- 2) The sensor is usually used in the common indoor environment. So some protection must be added if using in the conditions as followed:
 - a) The time of concentration $\geqslant 300 \mu$ g/m³ is longer than 50% of the whole year or concentration $\geqslant 500 \mu$ g/m³ is longer than 20% of the whole year.
 - b) Kitchen
 - c) Water mist condition such as bathroom or hot spring.
 - d) outdoor

Part Number Definition



Physical Size (mm)



Appendix I: PMS5003 transport protocol-Active Mode

Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

32 Bytes

| 0x42 | (Fixed) |
|------|--|
| 0x4d | (Fixed) |
| | Frame length=2x13+2(data+check bytes) |
| | |
| | Data1 refers to PM1.0 concentration unit µ g/m3 (CF=1, standard particle) * |
| | |
| | Data2 refers to PM2.5 concentration unit µ g/m3 (CF=1, standard particle) |
| | μ g/mo (Or -1, standard particle) |
| | Data3 refers to PM10 concentration unit µ g/m3 (CF=1, standard particle) |
| | μ g/mo (Cr = r, standard particle) |
| | Data4 refers to PM1.0 concentration unit * µ g/m3 (under atmospheric environment) |
| | μ g/mo (under aumospheric environment) |
| | Data 5 refers to PM2.5 concentration unit |
| | _ μ g/m3(under atmospheric environment) |
| | Data 6 refers to concentration unit (under |
| | atmospheric environment) µ g/m3 |
| | |
| | Data7 indicates the number of particles with diameter beyond 0.3 um |
| | in 0.1 L of air. |
| | Data 8 indicates the number of particles with diameter beyond 0.5 um |
| | in 0.1 L of air. |
| | Data 9 indicates the number of |
| | particles with diameter beyond 1.0 um in 0.1 L of air. |
| | |
| | 0x4d |

| Data10 high 8 bits | Data10 indicates the number of particles with diameter beyond 2.5 in 0.1 L of air. | |
|-------------------------------|--|--|
| Data10 low 8 bits | in on E or ain. | |
| Data11 high 8 bits | Data11 indicates the number of particles with diameter beyond 5.0 um | |
| Data11 low 8 bits | in 0.1 L of air. | |
| Data12 high 8 bits | Data12 indicates the number of particles with diameter beyond 10 | |
| Data12 low 8 bits | in 0.1 L of air. | |
| Data13 high 8 bits | Data13 Reserved | |
| Data13 low 8 bits | | |
| Data and check high 8 bits | Check code=Start character 1+ Start character 2++data 13 Low 8 bits | |
| Data and check low 8 bits | | |

Note: CF=1 should be used in the factory environment

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Appendix II: PMS5003 transport protocol-Passive Mode

Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

Host Protocol

| Start Byte | Start Byte | Command | Data 1 | Data 2 | Verify Byte | Verify Byte |
|------------|------------|---------|--------|--------|-------------|-------------|
| 1 | 2 | | | | 1 | 2 |
| 0x42 | 0x4d | CMD | DATAH | DATAL | LRCH | LRCL |
| | | | | | | |

1. Command Definition

| CMD | DATAH | DATAL | 说明 |
|------|-------|-------------|-----------------|
| 0xe2 | X | X | Read in passive |
| | | | mode |
| 0xe1 | X | 00H-passive | Change mode |
| | | 01H-active | |
| 0xe4 | X | 00H-sleep | Sleep set |
| | | 01H-wakeup | |

2. Answer

Oxe2: 32 bytes , same as appendix I

3. Verify Bytes:

Add of all the bytes except verify bytes.